Characterised control valve with sensor-operated flow rate or power control with fail-safe, power and energy-monitoring function, 2-way, Internal thread, PN 25 (Energy Valve)
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid, Cloud
- For closed cold and warm water systems
- For modulating control of air-handling and heating systems on the water side
- Ethernet 10/100 Mbit/s, TCP/IP, integrated web server
- Communication via BACnet, Modbus, Belimo MP-Bus or conventional control
- optional Belimo Cloud connection

Type overview

<table>
<thead>
<tr>
<th>Type</th>
<th>DN [ ]</th>
<th>Rp [°]</th>
<th>V'nom [ l/s]</th>
<th>V'nom [ l/min]</th>
<th>V'nom [ m³/h]</th>
<th>kvs theor. [ m³/h]</th>
<th>PN [ ]</th>
</tr>
</thead>
<tbody>
<tr>
<td>EV015R+KBAC</td>
<td>15</td>
<td>1/2</td>
<td>0.35</td>
<td>21</td>
<td>1.26</td>
<td>2.9</td>
<td>25</td>
</tr>
<tr>
<td>EV020R+KBAC</td>
<td>20</td>
<td>3/4</td>
<td>0.65</td>
<td>39</td>
<td>2.34</td>
<td>4.9</td>
<td>25</td>
</tr>
<tr>
<td>EV025R+KBAC</td>
<td>25</td>
<td>1</td>
<td>1.15</td>
<td>69</td>
<td>4.14</td>
<td>8.6</td>
<td>25</td>
</tr>
<tr>
<td>EV032R+KBAC</td>
<td>32</td>
<td>1 1/4</td>
<td>1.8</td>
<td>108</td>
<td>6.48</td>
<td>14.2</td>
<td>25</td>
</tr>
<tr>
<td>EV040R+KBAC</td>
<td>40</td>
<td>1 1/2</td>
<td>2.5</td>
<td>150</td>
<td>9</td>
<td>21.3</td>
<td>25</td>
</tr>
<tr>
<td>EV050R+KBAC</td>
<td>50</td>
<td>2</td>
<td>4.8</td>
<td>288</td>
<td>17.28</td>
<td>32.0</td>
<td>25</td>
</tr>
</tbody>
</table>

kvs theor.: Theoretical kvs value for pressure drop calculation

Technical data

**Electrical data**
- Nominal voltage: AC/DC 24 V
- Nominal voltage frequency: 50/60 Hz
- Nominal voltage range: AC 19.2...28.8 V / DC 21.6...28.8 V
- Power consumption in operation: 15 W
- Power consumption in rest position: 6.5 W
- Power consumption for wire sizing: 26 VA
- Connection supply / control: Cable 1 m, 6 x 0.75 mm²
- Connection Ethernet: RJ45 socket
- Parallel operation: Yes (note the performance data)

**Functional data**
- Torque motor: 20Nm
- Communicative control: BACnet IP, BACnet MS/TP, Modbus TCP, Modbus RTU, MP-Bus, Cloud
- Operating range Y: 2...10 V
- Input Impedance: 100 kΩ
- Operating range Y variable: 0.5...10 V
- Position feedback U: 2...10 V
- Position feedback U note: Max. 1 mA
- Position feedback U variable: 0...10 V, 0.5...10 V
- Setting fail-safe position: NC/NO or adjustable 0...100% (POP rotary knob)
- Running time fail-safe: 35 s / 90°
- Sound power level Motor: 45 dB(A)
- Sound power level, fail-safe: 61 dB(A)
- Adjustable flow rate V'max: 30...100% of Vnom
- Control accuracy: ±5% (of 25...100% V'nom) @ 20°C / Glycol 0% vol.
- Control accuracy note: ±10% (of 25...100% V'nom) @ -10...120°C / Glycol 0...50% vol.
- Min. controllable flow: 1% of V'nom
## Functional data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parametrisation</td>
<td>via integrated web server / ZTH EU</td>
</tr>
<tr>
<td>Fluid</td>
<td>Cold and warm water, water with glycol up to max. 50% vol.</td>
</tr>
<tr>
<td>Fluid temperature</td>
<td>-10...120°C</td>
</tr>
<tr>
<td>Fluid temperature note</td>
<td>At a fluid temperature of -10...2°C, a stem heating or a valve neck extension is recommended.</td>
</tr>
<tr>
<td>Close-off pressure $\Delta p_s$</td>
<td>1400 kPa</td>
</tr>
<tr>
<td>Differential pressure $\Delta p_{max}$</td>
<td>350 kPa</td>
</tr>
<tr>
<td>Differential pressure note</td>
<td>For low-noise operation</td>
</tr>
<tr>
<td>Flow characteristic</td>
<td>Equal percentage (VDI/VDE 2178), optimised in the opening range (switchable to linear)</td>
</tr>
<tr>
<td>Leakage rate</td>
<td>Air-bubble tight, leakage rate A (EN 12266-1)</td>
</tr>
<tr>
<td>Pipe connection</td>
<td>Internal thread according to ISO 7-1</td>
</tr>
<tr>
<td>Installation position</td>
<td>Upright to horizontal (in relation to the stem)</td>
</tr>
<tr>
<td>Servicing</td>
<td>Maintenance-free</td>
</tr>
<tr>
<td>Manual override</td>
<td>With push-button</td>
</tr>
</tbody>
</table>

### Flow measurement

<table>
<thead>
<tr>
<th>Metric</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measuring principle</td>
<td>Ultrasonic volumetric flow measurement</td>
</tr>
<tr>
<td>Measuring accuracy flow</td>
<td>±2% of (25...100% $V_{nom}$) / 20°C / Glycol 0% vol.</td>
</tr>
<tr>
<td>Measuring accuracy flow note</td>
<td>±6% of (25...100% $V_{nom}$) / -10...120°C / Glycol 0...50% vol.</td>
</tr>
<tr>
<td>Min. flow measurement</td>
<td>0.5% of $V_{nom}$</td>
</tr>
</tbody>
</table>

### Temperature measurement

<table>
<thead>
<tr>
<th>Metric</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measuring accuracy absolute temperature</td>
<td>± 0.35°C @ 10°C (Pt1000 EN60751 Class B) / ± 0.6°C @ 60°C (Pt1000 EN60751 Class B)</td>
</tr>
<tr>
<td>Measuring accuracy temperature difference</td>
<td>±0.18 K @ $\Delta T = 10$ K / ±0.23 K @ $\Delta T = 20$ K</td>
</tr>
<tr>
<td>Resolution</td>
<td>0.05°C</td>
</tr>
</tbody>
</table>

### Safety

<table>
<thead>
<tr>
<th>Metric</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protection class IEC/EN</td>
<td>III Protective extra-low voltage (PELV)</td>
</tr>
<tr>
<td>Degree of protection IEC/EN</td>
<td>IP40</td>
</tr>
<tr>
<td>Degree of protection note</td>
<td>IP54 when using protective cap or protective grommet for RJ45 socket</td>
</tr>
<tr>
<td>EMC</td>
<td>CE according to 2014/30/EU</td>
</tr>
<tr>
<td>Mode of operation</td>
<td>Type 1.AA</td>
</tr>
<tr>
<td>Rated impulse voltage supply</td>
<td>0.8 kV</td>
</tr>
<tr>
<td>Control pollution degree</td>
<td>3</td>
</tr>
<tr>
<td>Ambient temperature</td>
<td>-30...50°C</td>
</tr>
<tr>
<td>Storage temperature</td>
<td>-40...80°C</td>
</tr>
<tr>
<td>Ambient humidity</td>
<td>Max. 95% r.H., non-condensing</td>
</tr>
</tbody>
</table>

### Materials

<table>
<thead>
<tr>
<th>Material</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Flow measuring pipe</td>
<td>Brass body nickel-plated</td>
</tr>
<tr>
<td>Closing element</td>
<td>Stainless steel</td>
</tr>
<tr>
<td>Stem seal</td>
<td>EPDM O-ring</td>
</tr>
<tr>
<td>Immersion sleeve</td>
<td>Brass</td>
</tr>
<tr>
<td>T-Piece</td>
<td>Nickel-plated brass body</td>
</tr>
</tbody>
</table>

### Terms

<table>
<thead>
<tr>
<th>Metric</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviations</td>
<td>POP = Power off position / fail-safe position</td>
</tr>
</tbody>
</table>

### Safety notes

- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
Mode of operation

The HVAC performance device is comprised of four components: characterised control valve (CCV), measuring pipe with volumetric flow sensor, temperature sensors and the actuator itself. The adjusted maximum flow ($V_{\text{max}}$) is assigned to the maximum positioning signal (typically 10 V / 100%). Alternatively, the positioning signal can be assigned to the valve opening angle or to the power required on the heat exchanger (see power control). The HVAC performance device can be controlled communicative or analogue. The fluid is detected by the sensor in the measuring pipe and is applied as the flow value. The measured value is balanced with the setpoint. The actuator corrects the deviation by changing the valve position. The angle of rotation $\alpha$ varies according to the differential pressure through the final controlling element (see flow rate curves).

With the supply voltage the integrated condensors will be charged. Interrupting the supply voltage causes the valve to be moved to the selected fail-safe position by means of stored electrical energy.

Flow characteristic

Flow rate curves

\[ \Delta p_1 < \Delta p_2 < \Delta p_3 \]

Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position. The duration of the pre-charging time depends mainly on how long the power was interrupted.

Typical pre-charging time


table

<table>
<thead>
<tr>
<th>[d]</th>
<th>[s]</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>6</td>
</tr>
<tr>
<td>1</td>
<td>9</td>
</tr>
<tr>
<td>2</td>
<td>11</td>
</tr>
<tr>
<td>7</td>
<td>16</td>
</tr>
<tr>
<td>&gt;10</td>
<td>20</td>
</tr>
</tbody>
</table>

[<] = Electricity interruption in days
[<] = Pre-charging time in seconds

Delivery condition (capacitors)

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

Setting fail-safe position (POP)

The rotary knob fail-safe position can be used to adjust the desired fail-safe position 0...100% in 10% increments. The rotary knob always refers to the adapted angle of rotation range. In the event of a power failure, the actuator will move into the selected fail-safe position.
Transmission behaviour HE

Depending on the construction, temperature spread, fluid characteristics and hydraulic circuit, the power Q is not proportional to the water volumetric flow V (Curve 1). With the classical type of temperature control, an attempt is made to maintain the control signal Y proportional to the power Q (Curve 2). This is achieved by means of an equal-percentage valve characteristic curve (Curve 3).

Power control

Alternatively, the positioning signal Y can be assigned to the output power required on the heat exchanger. Depending on the water temperature and air conditions, the Energy Valve ensures the amount of water required to achieve the desired power.

Maximum controllable power on heat exchanger in power control mode:

<table>
<thead>
<tr>
<th>DN</th>
<th>Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>15</td>
<td>80 kW</td>
</tr>
<tr>
<td>20</td>
<td>140 kW</td>
</tr>
<tr>
<td>25</td>
<td>250 kW</td>
</tr>
<tr>
<td>32</td>
<td>380 kW</td>
</tr>
<tr>
<td>40</td>
<td>530 kW</td>
</tr>
<tr>
<td>50</td>
<td>1010 kW</td>
</tr>
</tbody>
</table>

Control characteristics

The specially configured control parameters in connection with the precise velocity sensor ensure a stable quality of control. They are, however, not suitable for rapid control processes, i.e. for domestic water control.

Definition

Flow control

V'nom is the maximum possible flow.

V'max is the maximum flow rate which has been set with the greatest positioning signal. V'max can be set between 30% and 100% of V'nom.
**Definition**

Power control

- **Q'nom** is the maximum possible power output on the heat exchanger.
- **Q'max** is the maximum power output on the heat exchanger which has been set with the greatest positioning signal. Q'max can be set between 1% and 100% of Q'nom.
- **Q'min** 0% (non-variable).

![Graph of Q [kW] vs Y [V]](attachment:image)

**Creep flow suppression**

Given the very low flow speed in the opening point, this can no longer be measured by the sensor within the required tolerance. This range is overridden electronically.

**Opening valve**
The valve remains closed until the volumetric flow required by the positioning signal Y corresponds to 1% of V'nom. The control along the valve characteristic curve is active after this value has been exceeded.

**Closing valve**
The control along the valve characteristic curve is active up to the required flow rate of 1% of V'nom. Once the level falls below this value, the flow rate is maintained at 1% of V'nom. If the level falls below the flow rate of 0.5% of V'nom required by the reference variable Y, then the valve will close.

![Graph of flow rate vs Y] (attachment:image)
Communication
The parametrisation can be carried out through the integrated web server (RJ45 connection to the web browser) or by communicative means. Additional information regarding the integrated web server can be found in the separate documentation.

“Peer to Peer” connection
http://belimo.local:8080
The Notebook must be set to “DHCP”.
Make sure that only one network connection is active.

Standard IP address:
http://192.168.0.10:8080
Static IP address

Password (read-only):
User name: «guest»
Password: «guest»

Positioning signal inversion
This can be inverted in cases of control with an analogue positioning signal. The inversion causes the reversal of the standard behaviour, i.e. at a positioning signal of 0%, regulation is to V’max or Q’max, and the valve is closed at a positioning signal of 100%.

Hydraulic balancing
Via the integrated web server, the maximum flow rate (equivalent to 100% requirement) can be adjusted on the device itself, simply and reliably, in a few steps. If the device is integrated in the management system, then the balancing can be handled directly by the management system.

Delta-T manager
If a heating or cooling register is operated with a differential temperature that is too low and thus with a flow rate that is too high, this will not result in an increased power output. Nevertheless, heating or cooling machines must provide the energy at a lower degree of efficiency. This means, that pumps circulate too much water and increase energy consumption unnecessarily.

With the aid of the Energy Valve, it is simple to discover that operation is being carried out at a differential temperature that is too low, resulting in the inefficient use of energy. Necessary setting adjustments can now be carried out quickly and easily at any time. The integrated differential temperature limiting offers the user the possibility of defining a low limit value. The Energy Valve limits the flow rate automatically to prevent the level from falling below this value.

The settings of the Delta-T manager can be made either directly on the web server or via the Belimo Cloud a direct analysis of the Delta-T behavior is carried out by Belimo experts.

Power output of the heating or cooling registers
1. Diff. temperature between supply and return
2. Loss zone (heating or cooling register saturation)
3. Adjustable minimum differential temperature

Combination analogue - communicative (hybrid mode)
With conventional control by means of an analogue positioning signal, the integrated web server, BACnet, Modbus or MP-Bus can be used for the communicative position feedback.
Power and energy monitoring function
The final controlling device is equipped with two temperature sensors. A sensor (T2) must be installed at the valve and the second sensor (T1) must be installed on-site on the other side of the water circulation. The two sensors are enclosed with the system already wired. The sensors are used to record the fluid temperature of the supply and return lines of the consumer (heating/cooling coil). As the water quantity is also known, thanks to the volumetric flow measurement integrated in the system, the power released from the consumer can be calculated. Furthermore, the heating/cooling energy is also determined automatically by means of the evaluation of the power over time.

The current data, e.g. temperatures, volumetric flow volumes, exchanger energy consumption etc. can be recorded and accessed at any time by means of web browsers or communication.

Data recording
The recorded data (integrated data recording for 13 months) can be used for the optimisation of the overall system and for the determination of the performance of the consumer.

Belimo Cloud
Additional Services are available, if the Energy Valve is connected to the Belimo Cloud: for instance, several devices may be managed via Internet. Also Belimo experts may help analyse the delta-T behavior or provide written reports about the Energy Valve performance. Under certain conditions, the product warranty according to the applicable Terms and Conditions of Sale may be prolonged. Further details may be found under [www.belimo.com/ext-warranty]

Manual override
Manual control with push-button possible - temporary. The gear is disengaged and the actuator decoupled for as long as the button is pressed.

High functional reliability
The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Electrical installation

**Notes**
- Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.
- The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS485 regulations.
- Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

---

**Accessories**

<table>
<thead>
<tr>
<th>Description</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grommet for RJ connection module, 50 pcs.</td>
<td>Z-STRJ.1</td>
</tr>
<tr>
<td>Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket</td>
<td>ZK1-GEN</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 15 Rp 1/2“</td>
<td>ZR2315</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 20 Rp 3/4“</td>
<td>ZR2320</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 25 Rp 1“</td>
<td>ZR2325</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 32 Rp 1 1/4“</td>
<td>ZR2332</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 40 Rp 1 1/2“</td>
<td>ZR2340</td>
</tr>
<tr>
<td>Pipe connector for ball valve DN 50 Rp 2“</td>
<td>ZR2350</td>
</tr>
<tr>
<td>Valve neck extension for ball valve DN15...50</td>
<td>ZR-EXT-01</td>
</tr>
<tr>
<td>Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators / VAV controller and HVAC performance devices</td>
<td>ZTH EU</td>
</tr>
</tbody>
</table>
**Electrical installation**

### Wiring diagrams

#### Conventional operation

![Wiring diagram](image)

**Cable colours:**
1 = black  
2 = red  
3 = white  
5 = orange  
6 = pink  
7 = grey

**Web-Browser**

- Connection of a notebook for parameterisation and manual control via RJ45.
- Optional connection via RJ45 (direct connection Notebook / connection via Intranet or Internet) for access to the integrated web server.

**MP-Bus, supply via 3-wire connection**

**MP-Bus via 2-wire connection, local power supply**

**MP-Bus Network topology**

- There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
- Supply and communication in one and the same 3-wire cable
- No shielding or twisting necessary
- No terminating resistors required

### Functions

#### Functions for devices with specific parameters (Parametrisation necessary)

**BACnet MS/TP / Modbus RTU**

![Wiring diagram](image)

- **C1 = D- = A**  
- **C2 = D+ = B**

---

**WEB-BROWSER**

**Y DC (0) 2...10 V**  
**U DC 2...10 V**

**CABLE COLOURS:**
1 = black  
2 = red  
3 = white  
5 = orange  
6 = pink  
7 = grey

**MP-BUS, SUPPLY VIA 3-WIRE CONNECTION**

**MP-BUS VIA 2-WIRE CONNECTION, LOCAL POWER SUPPLY**

**MP-BUS NETWORK TOPOLOGY**

- There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
- Supply and communication in one and the same 3-wire cable
- No shielding or twisting necessary
- No terminating resistors required

**FUNCTIONS**

**FUNCTIONS FOR DEVICES WITH SPECIFIC PARAMETERS (PARAMETRISATION NECESSARY)**

**BACNET MS/TP / MODBUS RTU**

![Wiring diagram](image)

- **C1 = D- = A**  
- **C2 = D+ = B**
**Functions**

**BACnet IP / Modbus TCP**

1) ~

**BACnet MS/TP / Modbus RTU with analog setpoint (hybrid mode)**

BACnet IP / Modbus TCP with analog setpoint (hybrid mode)

**MP-Bus with analog setpoint (hybrid mode)**

Override control and limiting with DC 24 V with relay contacts (with conventional control or hybrid mode)

1) Position control
2) Flow control
3) Power control

**Override control and limiting with DC 24 V with relay contacts (with conventional control or hybrid mode)**

**Electr. 2-way PI-CCV Belimo Energy Valve™ with fail-safe function, Internal thread, PN 25**

**www.belimo.com**
**Operating controls and indicators**

1. **LED display green**
   - Off: No power supply or wiring errors
   - On: In operation
   - Flickering: Internal communication (Valve/Sensor)

2. **Cover, POP button**

3. **POP button**

4. **Scale for manual adjustment**

5. **Push-button and LED display yellow**
   - On: Adaptation process active
   - Flashing: POP function active
   - Off: Not in operation, pre-charging time SuperCap, fault SuperCap
   - Press button: Triggers angle of rotation adaptation, followed by standard mode

6. **Gear disengagement button**
   - Press button: Gear disengages, motor stops, manual override possible
   - Release button: Gear engages, followed by standard mode

7. **Service plug**
   - For connecting the ZTH EU

---

Setting emergency setting position (POP)
Recommended installation positions

The ball valve can be installed upright to horizontal. The ball valve may not be installed in a hanging position, i.e. with the stem pointing downwards.

Mounting position in the return

Installation in the return is recommended.

Water quality requirements

The water quality requirements specified in VDI 2035 must be adhered to. Belimo valves are regulating devices. For the valves to function correctly in the long term, they must be kept free from particle debris (e.g. welding beads during installation work). The installation of a suitable strainer is recommended.

Servicing

Ball valves, rotary actuators and sensors are maintenance-free. Before any service work on the final controlling device is carried out, it is essential to isolate the rotary actuator from the power supply (by unplugging the electrical cable if necessary). Any pumps in the part of the piping system concerned must also be switched off and the appropriate slide valves closed (allow all components to cool down first if necessary and always reduce the system pressure to ambient pressure level).

The system must not be returned to service until the ball valve and the rotary actuator have been correctly reassembled in accordance with the instructions and the pipeline has been refilled by professionally trained personnel.

Flow direction

The direction of flow, specified by an arrow on the housing, is to be complied with, since otherwise the flow rate will be measured incorrectly.

Inlet section

In order to achieve the specified measuring accuracy, a flow-calming section or inflow section in the direction of the flow is to be provided upstream from the flow sensor. Its dimensions should be at least 5x DN.
Installation of immersion sleeve and temperature sensor

The valve is equipped with two fully-wired temperature sensors.
• T2: This sensor is installed on site near the valve unit.
• T1: This sensor is installed on site ahead of the consumer (valve in the return line) or after the consumer (valve in the supply line).

Two T-pieces for installation of the temperature sensors in the pipelines are included in the shipment.

Note
The cables between valve unit and temperature sensors may not be either shortened or lengthened.

Split installation
The valve-actuator combination may be mounted separately from the flow sensor. The direction of flow must be observed.

General notes

Valve selection
The valve is determined using the maximum required flow rate $V'_{\text{max}}$.
A calculation of the $k_{\text{vs}}$ value is not required.
$V'_{\text{max}} = 30\ldots100\%$ of $V'_{\text{nom}}$
If no hydraulic data are available, then the same valve DN can be selected as the heat exchanger nominal diameter.

Minimum differential pressure (pressure drop)
The minimum required differential pressure (pressure drop through the valve) for achieving the desired volumetric flow $V'_{\text{max}}$ can be calculated with the aid of the theoretical $k_{\text{vs}}$ value (see type overview) and the below-mentioned formula. The calculated value is dependent on the required maximum volumetric flow $V'_{\text{max}}$. Higher differential pressures are compensated for automatically by the valve.

Formula

$$\Delta p_{\text{min}} = 100 \times \left( \frac{V'_{\text{max}}}{k_{\text{vs theoretic}}} \right)^2$$

$\Delta p_{\text{min}}$: kPa
$V'_{\text{max}}$: m$^3$/h
$k_{\text{vs theoretic}}$: m$^3$/h

Example (DN25 with the desired maximum flow rate = 50% $V'_{\text{nom}}$)
EV025R+KBAC
$k_{\text{vs theoretic}} = 8.6$ m$^3$/h
$V'_{\text{nom}} = 69$ l/min
$50\% \times 69$ l/min = 34.5 l/min = 2.07 m$^3$/h

$$\Delta p_{\text{min}} = 100 \times \left( \frac{2.07 \text{ m}^3/\text{h}}{8.6 \text{ m}^3/\text{h}} \right)^2 = 6 \text{ kPa}$$

www.belimo.com
General notes

**Behaviour with sensor failure**
In case of a flow sensor error, the Energy Valve will switch from either power or flow control to position control (Delta-T manager will be deactivated).
Once the error disappears, the Energy Valve will switch back to the normal control setting (Delta-T manager activated).

**Dimensions / Weight**

<table>
<thead>
<tr>
<th>Type</th>
<th>DN</th>
<th>Rp</th>
<th>L</th>
<th>L1</th>
<th>L2</th>
<th>L3</th>
<th>L4</th>
<th>B</th>
<th>H</th>
<th>G1</th>
<th>X</th>
<th>Y</th>
<th>Weight</th>
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<td>EV015R+KBAC</td>
<td>15</td>
<td>1/2</td>
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<td>128</td>
<td>13</td>
<td>53</td>
<td>75</td>
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<td>14</td>
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<tr>
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<td>16</td>
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<td>255</td>
<td>110</td>
<td>19</td>
<td>71</td>
<td>75</td>
<td>168</td>
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<td>77</td>
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<td>71</td>
<td>75</td>
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<td>EV050R+KBAC</td>
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<td>288</td>
<td>100</td>
<td>22</td>
<td>80</td>
<td>75</td>
<td>177</td>
<td>G1/4&quot;</td>
<td>247</td>
<td>77</td>
<td>6.0 kg</td>
</tr>
</tbody>
</table>

Further documentation

- Overview MP Cooperation Partners
- Tool connections
- General notes for project planning
- Instruction Webserver
- Description Data-Pool Values
- Description Protocol Implementation Conformance Statement PICS
- Description Modbus register
- Introduction to MP-Bus Technology